

Construction Spaces for the Design of Learning Tasks in Virtual Worlds

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ECGBL 2014

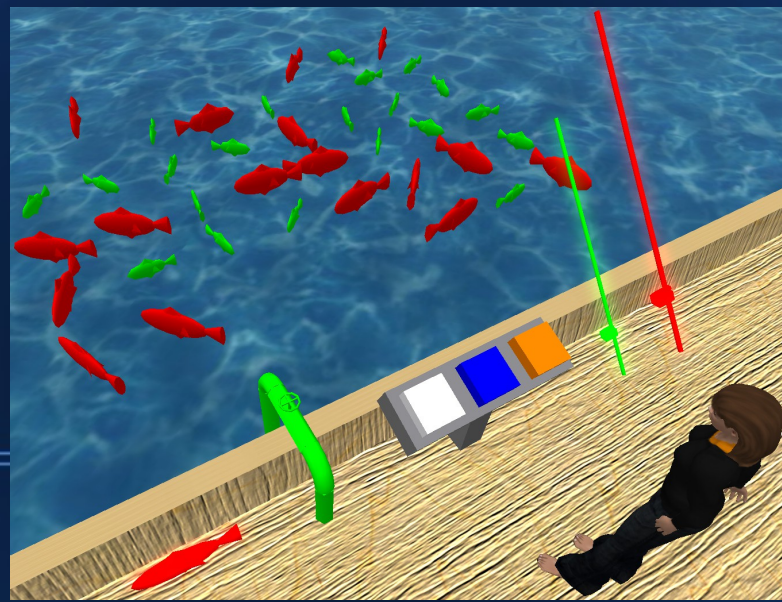
Agenda

- Problem Statement
- Study case
- Design approach
- Evaluation

Introduction and Problem Statement

Virtual Worlds in Education

- Multi-user virtual environments, e.g. *Second Life*
- Games, e.g. computer role-playing games
- Activities: Crafting, Conversations ...



Biology experiment
[OpenSim]

Literature game
[Neverwinter Nights]



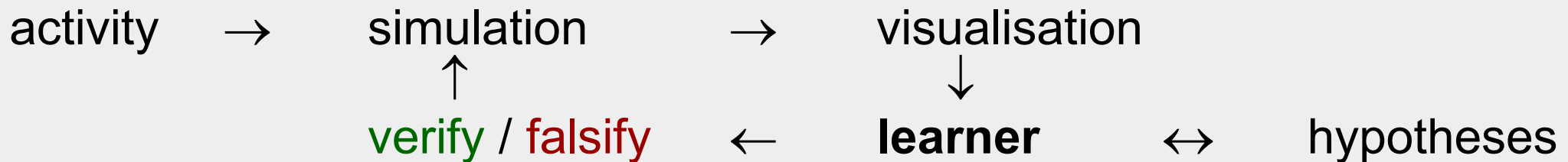
Ferdinand von Walter

Ich habe mich in Ihnen betrogen, Lady. Ich erwartete - ich wünschte, Sie meiner Verachtung würdig zu finden. Fest entschlossen, Sie zu beleidigen und Ihren Hass zu verdienen, empfing ich Sie - glücklich wir beide, wenn mein Vorsatz gelungen wäre! Ich liebe, Milady, liebe eine Bürgerliche - Luise Millerin, eines Musikus Tochter. Können Sie eine Hand ohne Herz erzwingen? Können Sie einem Mädchen den Mann entwenden?

1. Weil ich es muss. Meine Leidenschaft, Walter, weicht meiner Zärtlichkeit für Sie. Meine Ehre kann's nicht mehr. Unsre Verbindung ist das Gespräch des ganzen Landes. Alle Augen, alle Pfeile des Spotts, sind auf mich gespannt. Die Beschimpfung ist unauslöschlich, wenn ein Untertan des Fürsten mich ausschlägt. Wehren Sie sich, so gut Sie können. Ich lass alle Minen sprengen!
2. Walter, ich habe Kerker gesprengt - habe Todesurteile zerrissen und manche entsetzliche Ewigkeit auf Galeeren verkürzt. Und jetzt kommt der Mann, der allein mir das alles belohnen sollte. Der Mann, den mein unerschöpftes Schicksal vielleicht zum Ersatz meiner vorigen Leiden schuf. Der Mann, den ich mit brennender Sehnsucht im Traum schon umfasste... und sagt Nein??
3. Höre, Walter. Wenn eine Unglückliche - unwiderstehlich allmächtig an dich gezogen - sich an dich presst mit einem Busen voll glühender unerschöpflicher Liebe, Walter, und du jetzt noch kalte Worte sprichst... Wenn diese Unglückliche - niedergedrückt vom Gefühl ihrer Schande, des Lasters überdrüssig, heldenmässig emporgehoben vom Rufe der Tugend, sich so in deine Arme wirft....

Constructivist Learning

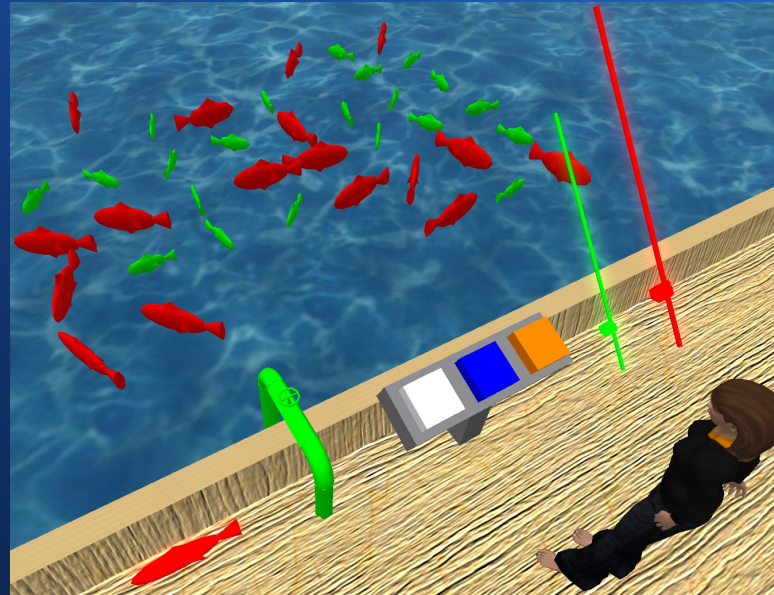
- So: virtual worlds can immerse students in interactive simulations of real world activities
- Constructivist view: own versions of domain knowledge (personal constructs, mental models)
- Or pave their own paths towards the knowledge
- Design: Simulations that inspire experimenting



Problem Statement: How Much Interactive Freedom?

Instruction

Design of activities
Choice of tasks
Feedback, hints
Reflection tools



Construction

Experimenting difficult ¹
Self-regulation skills
Lost in possibility space
Designer: Restrict freedom



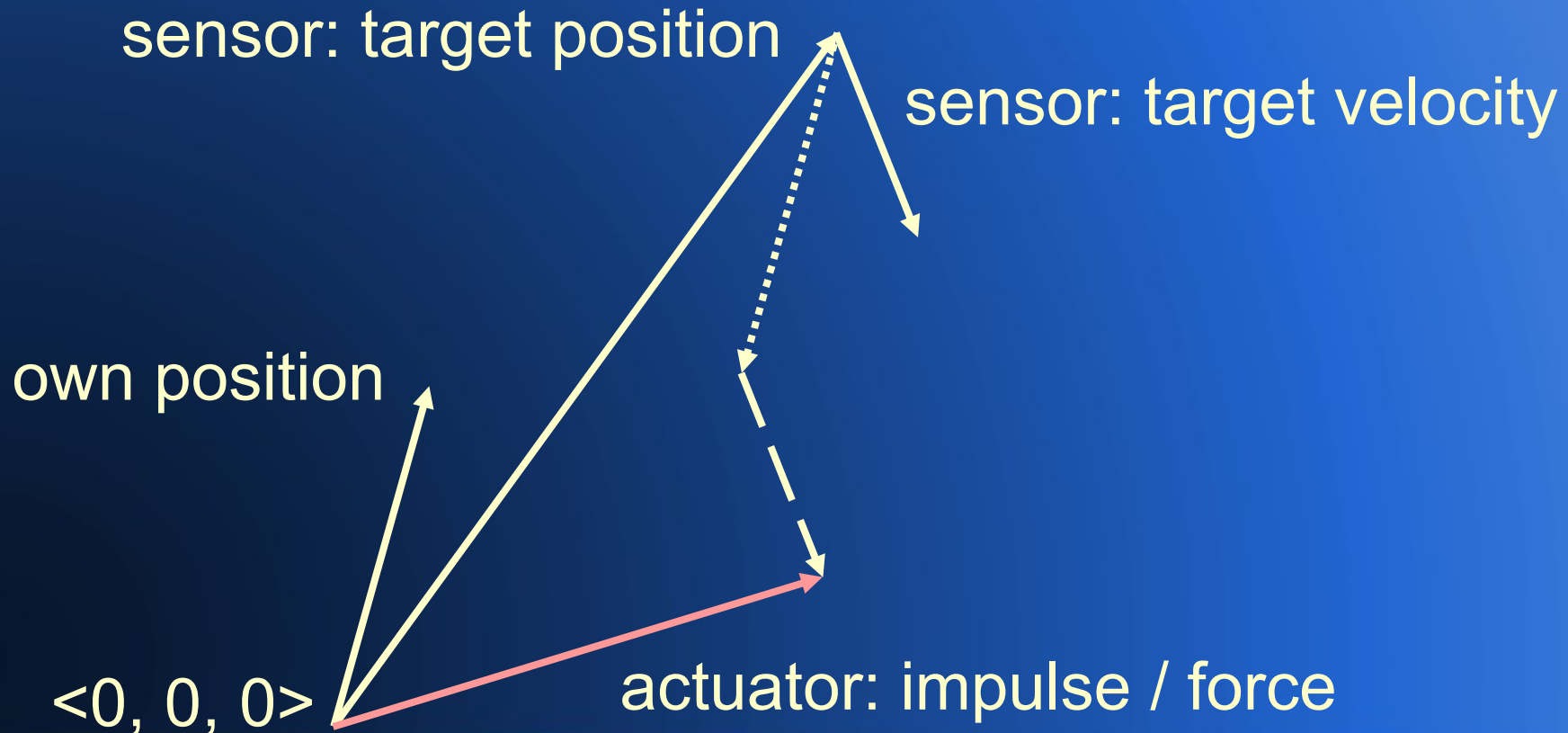
¹ de Jong & van Joolingen (1998): Scientific discovery learning with computer simulations of conceptual domains. *Review of Educational Research*, 68(2).

Study Case

Virtual Factory in *Second Life*

Applied Artificial Intelligence

Steering, e.g. Pursuit



Instructions in a Virtual Factory



Instructions in a Virtual Factory



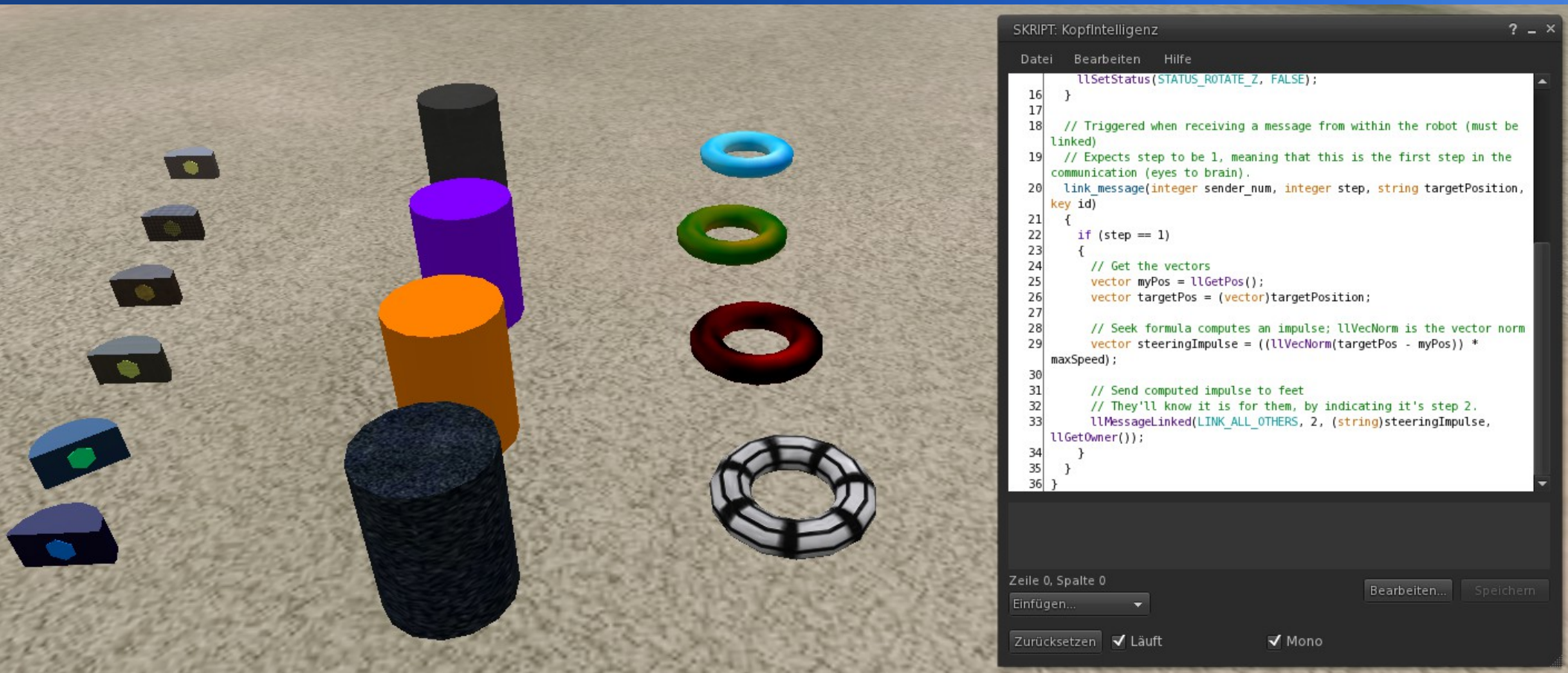
Instructions in a Virtual Factory



Instructions in a Virtual Factory

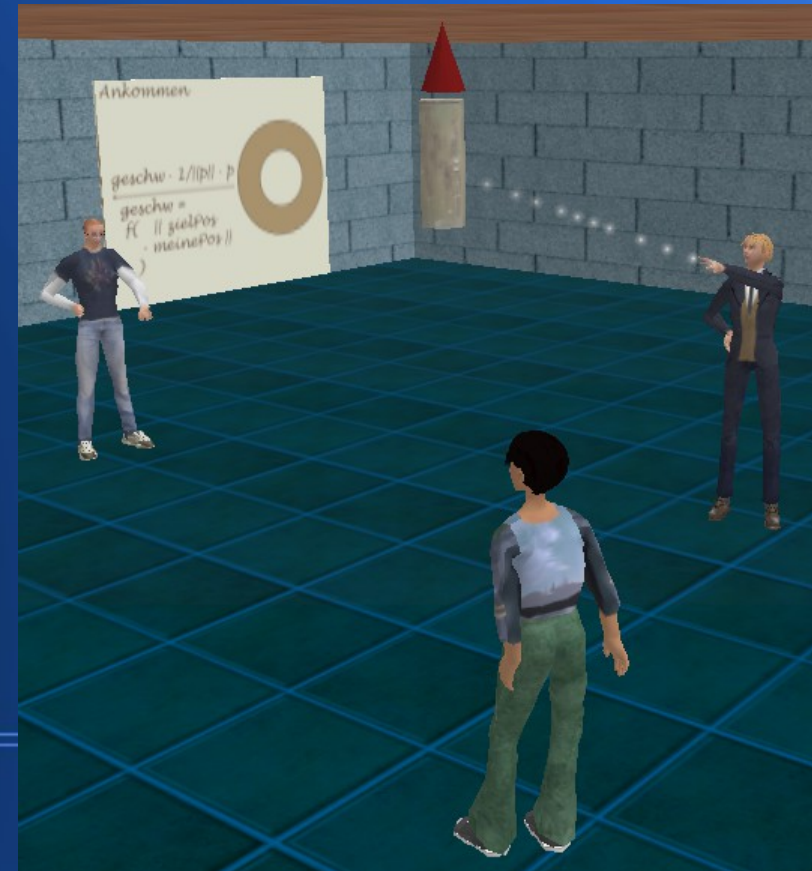
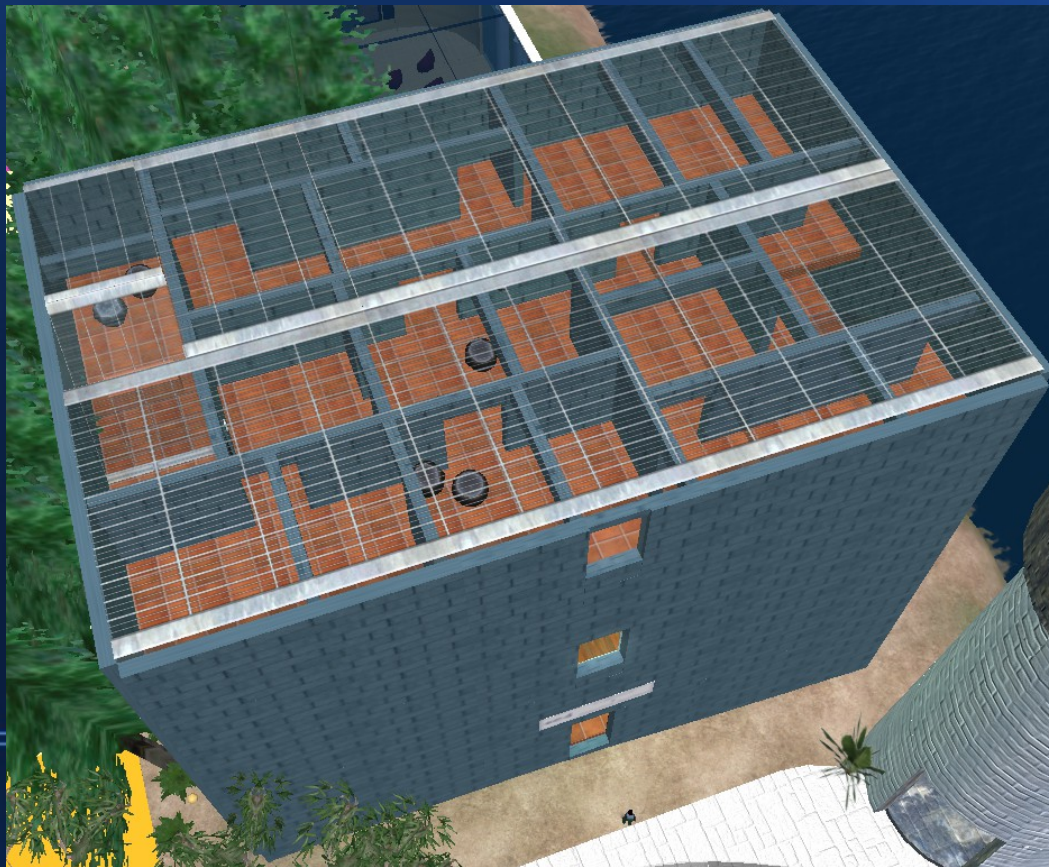


Construction: Crafting, Puzzles



Creativity & Inventions

- Appropriate level of difficulty at the right time
- Appropriate degree of instruction vs. construction



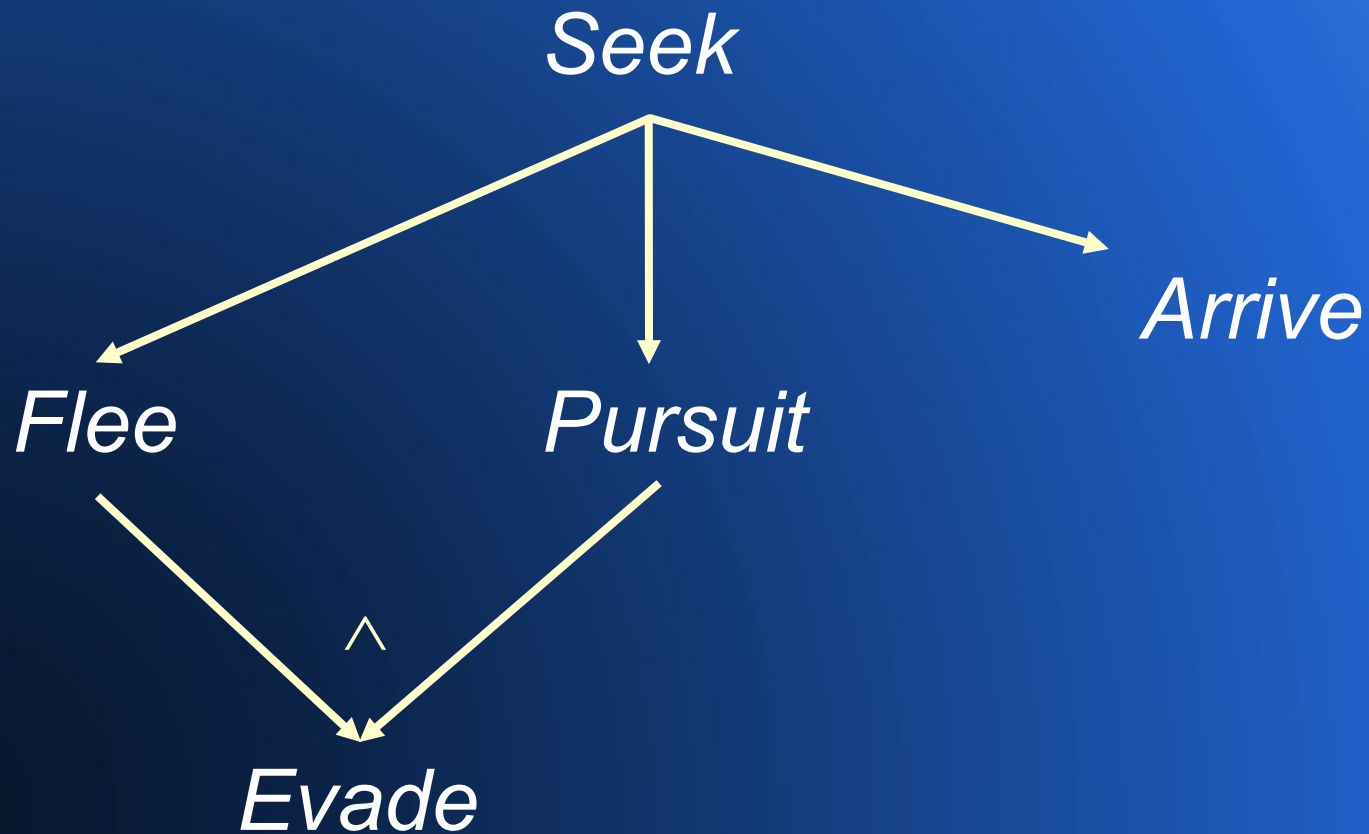
Design Approach

Construction Spaces

Set of Tasks

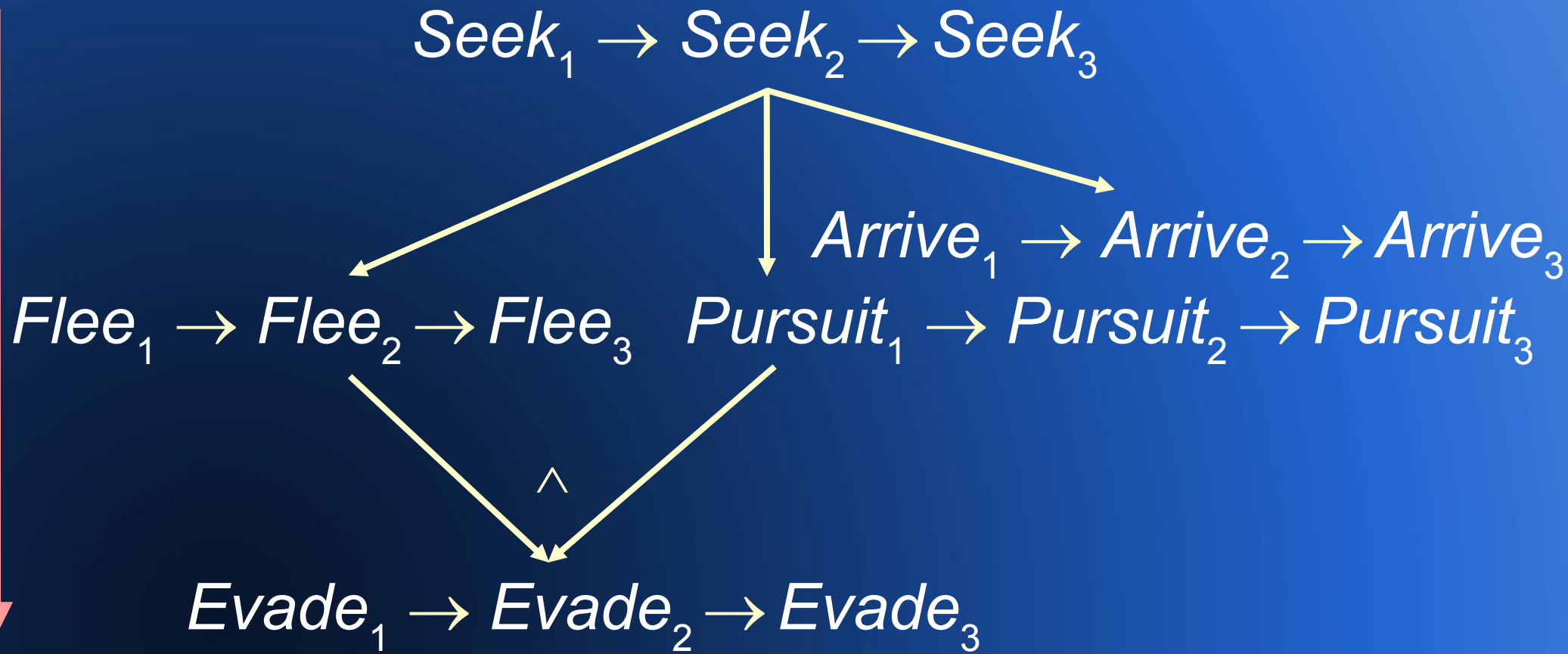
- *Seek* computes a vector to a target position
- *Flee* computes a *Seek* vector and reverses its orientation
- *Pursuit* computes a *Seek* vector to an anticipated future position of the target
- *Arrive* computes a *Seek* vector with deceleration
- *Evade* computes a *Flee* vector from an anticipated future position (reversed *Pursuit*)

Increasing Difficulty ²



² cf. Albert & Held (1999): Component-based knowledge spaces in problem solving and inductive reasoning. In Albert & Lukas (eds.): *Knowledge Spaces*.

Increasing Degree of Construction ³



³ cf. Collins, Brown & Newman (1987): Cognitive Apprenticeship.
Technical Report #403, Center for the Study of Reading, University of Illinois.

Manipulating → Constructing ⁴



```
SKRIPT: KopfIntelligenz
Datei Bearbeiten Hilfe
16 llSetStatus(STATUS_ROTATE_Z, FALSE);
17 }
18 // Triggered when receiving a message from within the robot (must be
19 // linked)
20 // Expects step to be 1, meaning that this is the first step in the
21 // communication (eyes to brain).
22 link_message(integer sender_num, integer step, string targetPosition,
23 key id)
24 {
25     if (step == 1)
26     {
27         // Get the vectors
28         vector myPos = llGetPos();
29         vector targetPos = (vector)targetPosition;
30
31         // Seek formula computes an impulse; llVecNorm is the vector norm
32         vector steeringImpulse = ((llVecNorm(targetPos - myPos)) *
33 maxSpeed);
34
35         // Send computed impulse to feet
36         // They'll know it is for them, by indicating it's step 2.
37         llMessageLinked(LINK_ALL_OTHERS, 2, (string)steeringImpulse,
38 llGetOwner());
39     }
40 }
41 }
```

Zeile 0, Spalte 0

Einfügen...

Zurücksetzen ☒ Läuft ☒ Mono

Bearbeiten... Speichern

³ cf. Schulmeister (2003): Taxonomy of Multimedia Component Interactivity. *Studies in Communication Sciences*, 3(3).

Evaluation

in the classroom

Setting & Hypotheses

- 12th grade, age 17–18, 11 male, 1 female
- 4 sessions, 90 minutes each, teams of 2
- Introductions, $Seek_1$, after that tasks assigned individually, traversing the construction space
- Hypotheses
 - Always medium challenge
 - Experimenting behaviour
 - Increasing degree of construction → creative ideas

Worksheets

A1

Gruppe _____
 Avatar _____

Zeit _____
 Passwort _____

Wie schwierig war die Aufgabe?

viel zu einfach


zu einfach

gerade richtig

zu schwierig

viel zu schwierig

Aufgabe: Wie funktioniert ANKOMMEN?
 Setzt Roboterteile aufeinander und fügt sie mit „STRG+L“ zusammen. Der Roboter soll eurem Avatar Schritt für Schritt folgen. Die Schritte werden aber kürzer, je näher er kommt!



Hat die Aufgabe Spaß gemacht?

nein

eher nein

geht so

eher ja

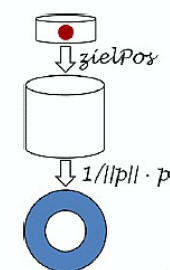
ja

Vermutungen

Tests

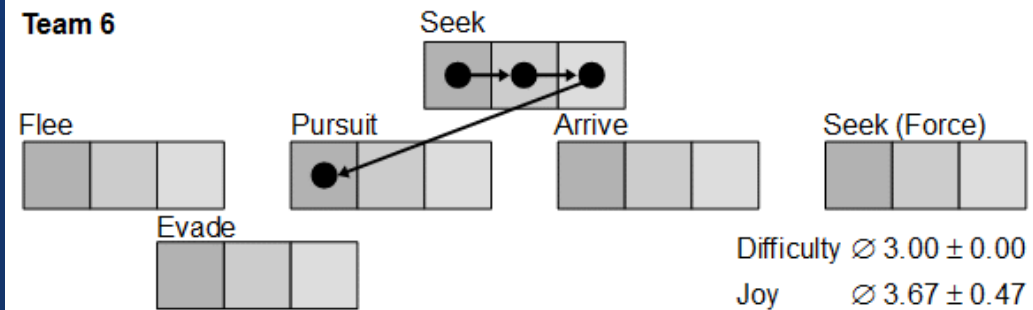
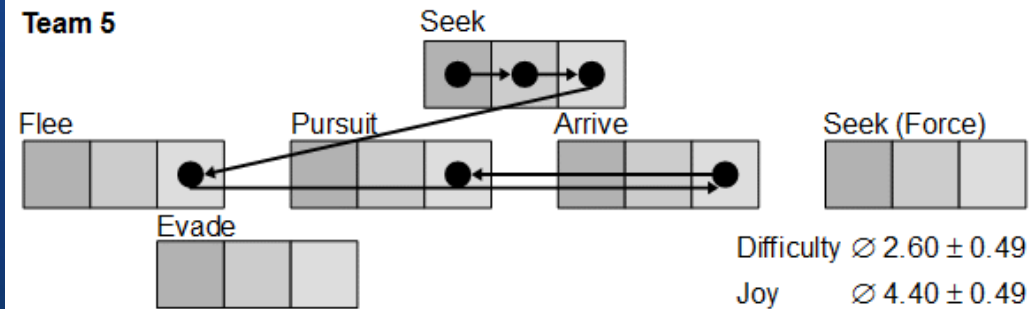
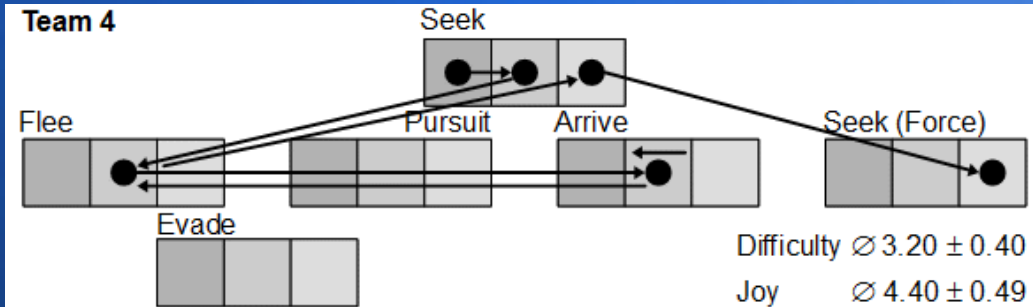
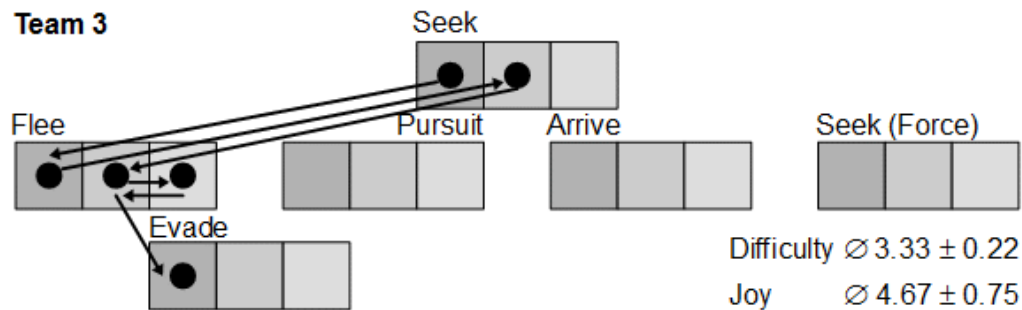
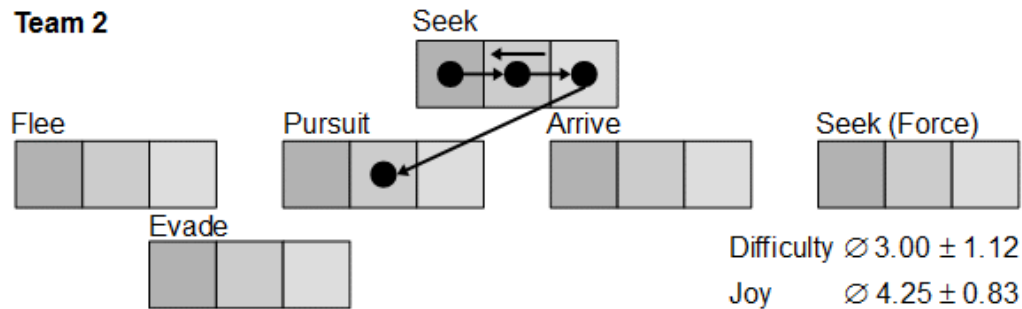
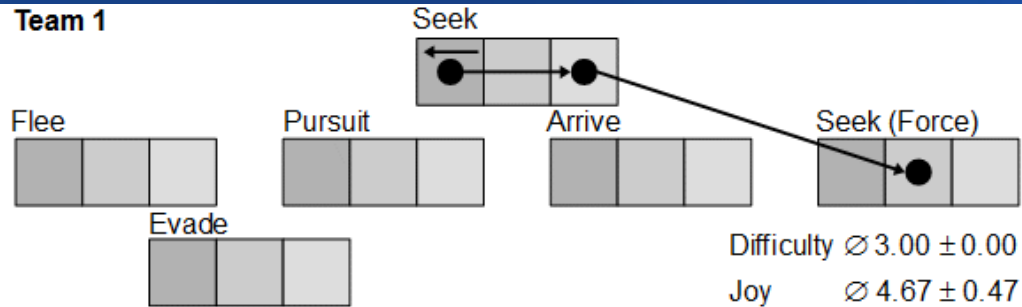
Ergebnisse

Welches Teil operiert anders als beim SUCHEN? Wie?

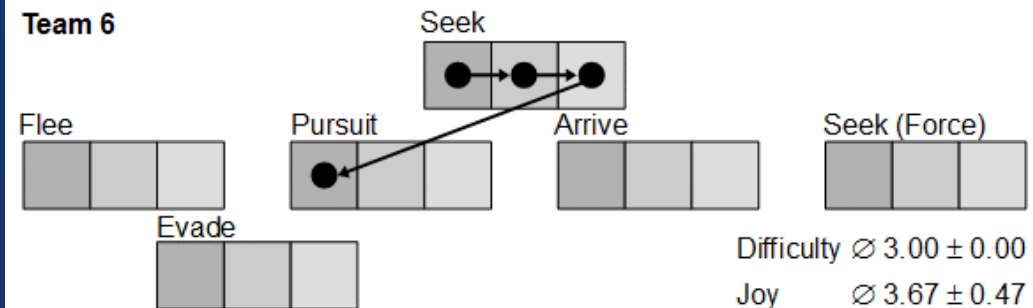
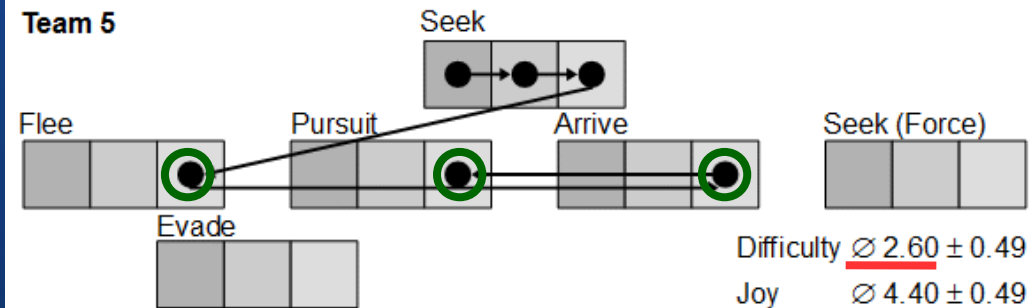
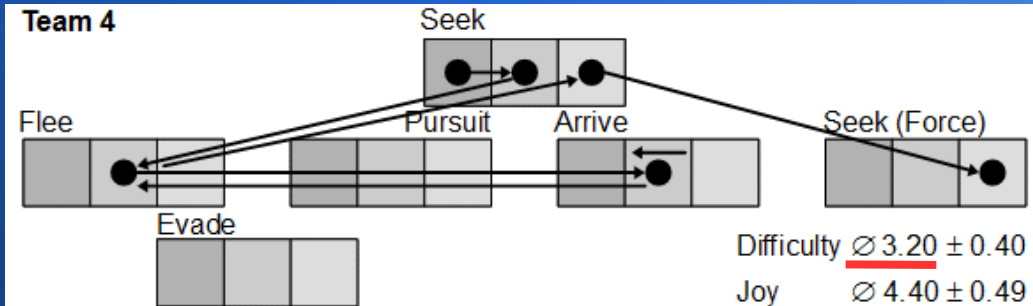
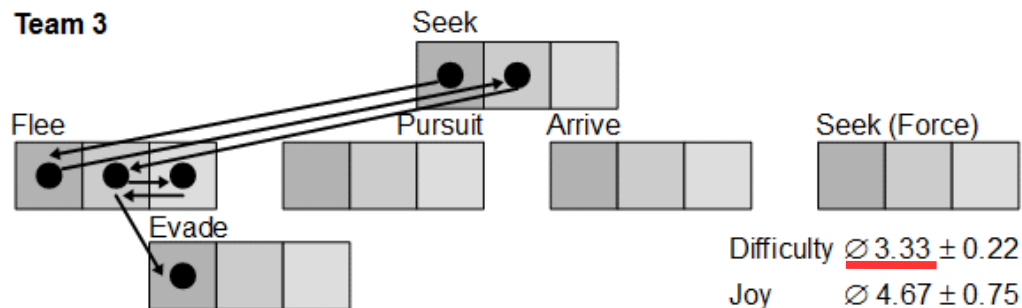
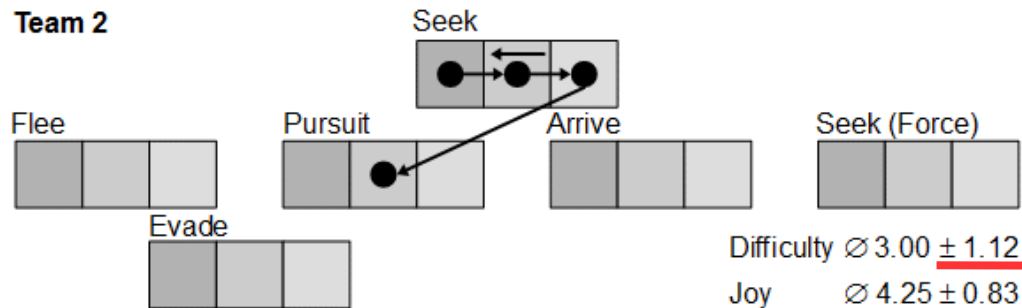
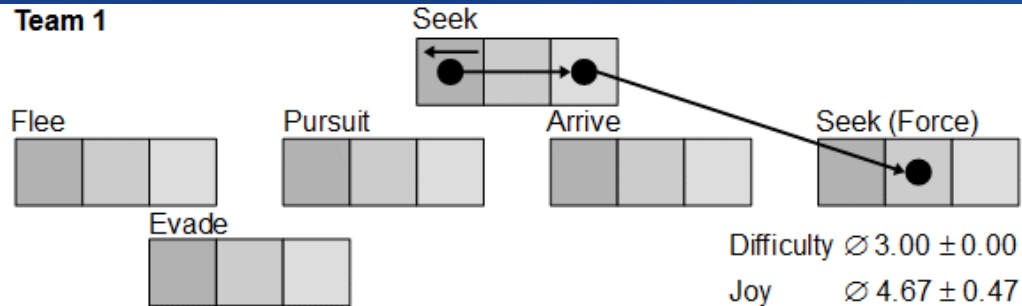


Was war besonders einfach / besonders schwierig?

Recorded Learning Paths (2D)



Joy, Difficulty, Learning Styles



Qualitative Results

- Narratives scarce, not precise, incorrect
- Understood in instant / didn't reflect, but continued
- Problems setting up experiments & documenting
- Except when following own, creative ideas
 - Code: seek own avatar, *Arrive* circle, rotation, gravity
 - Comparison: $Seek_1$; $Flee_1$; $Seek_2$; $Flee_2$
- Tried ideas quicker than could think them through:
They played!

Student Feedback

- + Trying out ideas (3 students)
- + Close to practice (4)
- + Direct application of knowledge/visual feedback (5)
- Too little theory (2) ← competent
- Too few coding instructions (2) ← struggling

Conclusions

- Two-dimensional model successful: Adapt to learning styles depth-first vs. breadth-first
- Experimenting works best with own ideas, but we have to support reflection in a better way
- Current work
 - Interactive learning journals (as quest journals)
 - Graphical representations of mental models
 - Automated suggestion of next actions

Thank you for your interest!

- Contact info
 - Dennis Maciuszek: info@storyautor.de
 - Alke Martens: alke.martens@uni-rostock.de
- Thank you, participants!
 - Bert Schröder, Erasmus-Gymnasium Rostock
 - 12th grade Computer Science course 2012/13

| | | | |
|-----|-----------------------|---------------|---|
| (1) | $\neg \text{Seek}$ | \Rightarrow | $\neg \text{Flee} \wedge \neg \text{Pursuit} \wedge \neg \text{Arrive}$ |
| (2) | $\neg \text{Flee}$ | \Rightarrow | $\neg \text{Evade}$ |
| (3) | $\neg \text{Pursuit}$ | \Rightarrow | $\neg \text{Evade}$ |

PDF download:
www.storyautor.de/userfiles/downloads/ecgbl2014.pdf

| | | | |
|------|-------------------------|---------------|---|
| (1') | $\neg \text{Seek}_i$ | \Rightarrow | $\neg \text{Flee}_1 \wedge \neg \text{Flee}_2 \wedge \neg \text{Flee}_3$ $\wedge \neg \text{Pursuit}_1 \wedge \neg \text{Pursuit}_2 \wedge \neg \text{Pursuit}_3$ $\wedge \neg \text{Arrive}_1 \wedge \neg \text{Arrive}_2 \wedge \neg \text{Arrive}_3$ |
| (2') | $\neg \text{Flee}_i$ | \Rightarrow | $\neg \text{Evade}_1 \wedge \neg \text{Evade}_2 \wedge \neg \text{Evade}_3$ |
| (3') | $\neg \text{Pursuit}_i$ | \Rightarrow | $\neg \text{Evade}_1 \wedge \neg \text{Evade}_2 \wedge \neg \text{Evade}_3$ |
| (4) | $\neg \text{Seek}_1$ | \Rightarrow | $\neg \text{Seek}_2$ |
| (5) | $\neg \text{Seek}_2$ | \Rightarrow | $\neg \text{Seek}_3$ |
| (6) | $\neg \text{Flee}_1$ | \Rightarrow | $\neg \text{Flee}_2$ |
| (7) | $\neg \text{Flee}_2$ | \Rightarrow | $\neg \text{Flee}_3$ |
| (8) | $\neg \text{Pursuit}_1$ | \Rightarrow | $\neg \text{Pursuit}_2$ |
| (9) | $\neg \text{Pursuit}_2$ | \Rightarrow | $\neg \text{Pursuit}_3$ |

| | | | |
|------|------------------------|---------------|------------------------|
| (10) | $\neg \text{Arrive}_1$ | \Rightarrow | $\neg \text{Arrive}_2$ |
| (11) | $\neg \text{Arrive}_2$ | \Rightarrow | $\neg \text{Arrive}_3$ |
| (12) | $\neg \text{Evade}_1$ | \Rightarrow | $\neg \text{Evade}_2$ |
| (13) | $\neg \text{Evade}_2$ | \Rightarrow | $\neg \text{Evade}_3$ |

| | | | |
|-------|-----------------------|---------------|---|
| (1'') | $\neg \text{Seek}_i$ | \Rightarrow | $\neg \text{Flee}_1 \wedge \neg \text{Flee}_2 \wedge \neg \text{Flee}_3$ $\wedge \neg \text{Pursuit}_1 \wedge \neg \text{Pursuit}_2 \wedge \neg \text{Pursuit}_3$ $\wedge \neg \text{Arrive}_1 \wedge \neg \text{Arrive}_2 \wedge \neg \text{Arrive}_3$ $\wedge \neg \text{Force}_1 \wedge \neg \text{Force}_2 \wedge \neg \text{Force}_3$ |
| (14) | $\neg \text{Force}_1$ | \Rightarrow | $\neg \text{Force}_2$ |
| (15) | $\neg \text{Force}_2$ | \Rightarrow | $\neg \text{Force}_3$ |

Students had problems setting up discovery learning experiments (which is also one issue in de Jong and van Joolingen 1998). For Seek_1 , some good entries document combinations: “Head 3, Foot 3, Eye 3 \Rightarrow fleeing robot; Head 1, Foot 1, Eye 1 \Rightarrow following robot; Head 2, Foot 2, Eye 2 \Rightarrow following robot.” Experiments with code parameters (range, angle, speed, name etc.) worked in practice, but